

Superheterodyne AM receiver

Typical Frequency Parameters of AM and FM radio receivers

15.10.2016

15:00-16:00

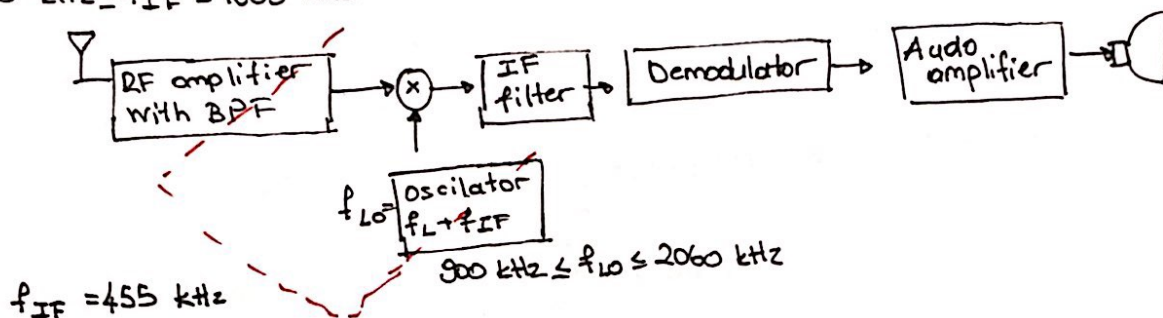
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RF carrier range AM 0.535-1.605 MHz FM 88-108 MHz

IF 0.455 MHz 10.7 MHz

IF bandwidth 10 kHz 200 kHz

535 kHz $\leq f_{IF} \leq$ 1605 kHz

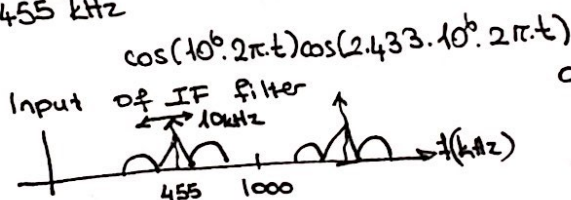


Example:

IF $f_c = 1000$ kHz

$f_{LO} = f_c + f_{IF} = 1000 + 455 = 1455$ kHz

Output of RF amplifier



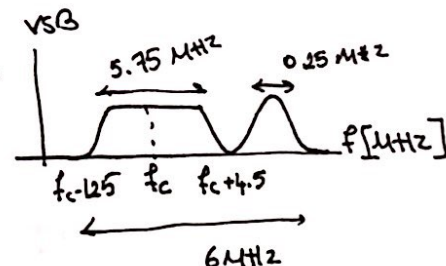
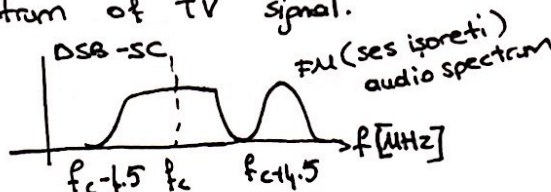
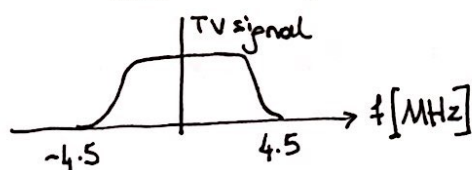
Output of IF filter



Television Signal

- Television signal exhibits a large bandwidth and significant low-frequency content.
- Suggest the use of Vestigial sideband modulation (VSB)

Idealized amplitude spectrum of TV signal.



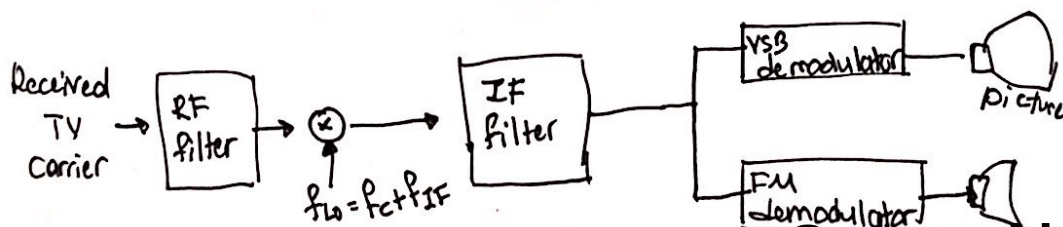
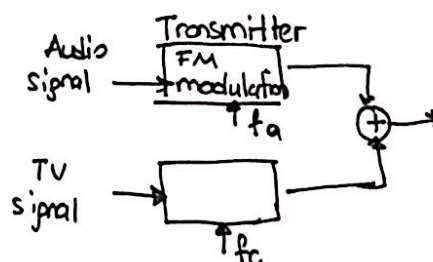
Tv channel Assignments

Channel number

VHF 2,3,4
VHF 5,6
UHF 14-83

Freq. Band [MHz]

54-72
76-88
470-890



Angle Modulation

- Advantage: It can provide better discrimination against noise and interference than amplitude modulation.

- Disadvantage: The cost of increased system complexity

$$s(t) = A_c \cos(\theta_i(t))$$

$\theta_i(t)$: instantaneous angle

$f_i(t)$: " frequency

$$\frac{d\theta_i(t)}{dt} = 2\pi f_i(t)$$

ANGLE MODULATION:

16.11.2016
14:00-16:00
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1) Phase Modulation (PM)

$$\theta_i(t) = 2\pi f_c t + k_p m(t)$$

anlık frekans

$m(t)$: message signal

k_p : Phase sensitivity factor

$$PM: s(t) = A_c \cos(2\pi f_c t + k_p m(t))$$

2) Frequency Modulation (FM)

$$\frac{1}{2\pi} \frac{d\theta_i(t)}{dt} = f_i(t)$$

$$f_i(t) = f_c + k_f m(t)$$

Anlık frekans önce anlık ağıya dönüştüren

k_f : Frequency sensitivity factor

$$\theta_i(t) = 2\pi \int_0^t f_i(\tau) d\tau = 2\pi \int_0^t f_c + k_f m(\tau) d\tau = 2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau$$

$$FM: s(t) = A_c \cos(2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau)$$

Properties of Angle Modulation (A_c değişmediğinden güç sabit kalacak.)

1. Constancy of transmitted power

$$P = \frac{A_c^2}{2}$$

//AM'de güç mesaj işaretine bağlıdır yon bantından geçse.

2. Doğrusal değil. $\cos(2\pi f_c t + k_p m(t))$ lineer değil.

Nonlinearity of modulation process

$$m_1(t) \rightarrow s_1(t) = A_c \cos(2\pi f_c t + k_p m_1(t))$$

$$m_2(t) \rightarrow s_2(t) = A_c \cos(2\pi f_c t + k_p m_2(t))$$

$$m_1(t) + m_2(t) \rightarrow s(t) = A_c \cos(2\pi f_c t + k_p (m_1(t) + m_2(t)))$$

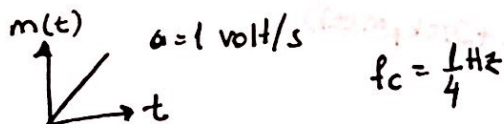
$$s(t) \neq s_1(t) + s_2(t) \quad \text{"Nonlinear"}$$

Faz modülasyonu ve frekans modülasyonu → LINEER değil

. genlik modülasyonunda double side bantda lineer.

3. Irregularity of zero-crossing

Example: $m(t) = \begin{cases} at, & t \geq 0 \\ 0, & t < 0 \end{cases}$

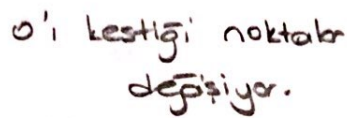


PM: phase modulation

$$s(t) = \begin{cases} A_c \cos(2\pi f_c t + k_p a t), & t \geq 0 \\ A_c \cos(2\pi f_c t), & t < 0 \end{cases}$$

$$A_c = 1 \text{ volt} \\ k_p = \frac{\pi}{2} \text{ rad/volt olsun.}$$

$m(t) = 0$ için + yok.



$k_p = \frac{\pi}{2} \rightarrow 2\pi$ 'de bir kendini tekrar

FM: $t \geq 0$

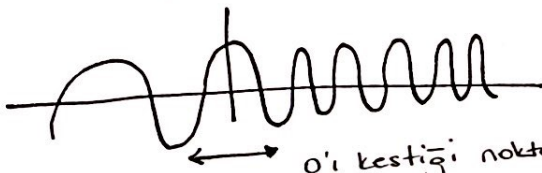
$$\theta_i(t) = 2\pi \int_0^t f_c + k_f m(\tau) d\tau = 2\pi f_c t + 2\pi k_f \int_0^t \alpha \tau d\tau = 2\pi f_c t + \pi k_f \alpha t^2$$

$$s(t) = \begin{cases} A_c \cos(2\pi f_c t + \pi k_f a t^2) & , t \geq 0 \\ A_c \cos(2\pi f_c t) & , t < 0 \end{cases}$$

$$\theta_i(t) = 2\pi \int_0^t f_c = 2\pi f_c t$$

$$k_f = 1 \text{ Hz/volt}$$

$A_c = 1 \text{ volt}$ olsun.



0'ı kestiği noktalar değişiyor.

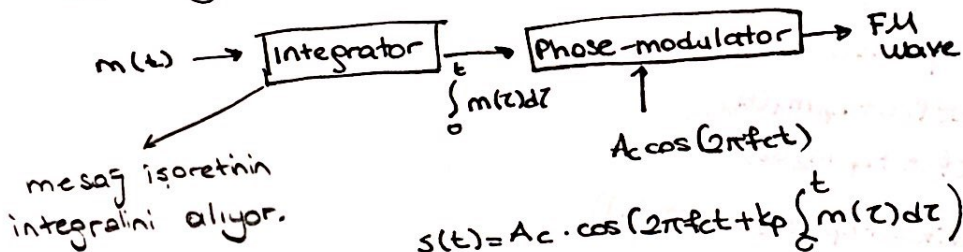
4. Visualization difficulty of message waveform →

Burada $s(t)$ 'ye
bakarak $m(t)$ 'yi anlamak zor.
Genlik mod'ünün zarfı mesaj
işaretini veriyordu.

5. Trade off increased transmission bandwidth for improved noise performance.

Relation between PM and FM waves

- Generating an FM wave by using a phase modulator



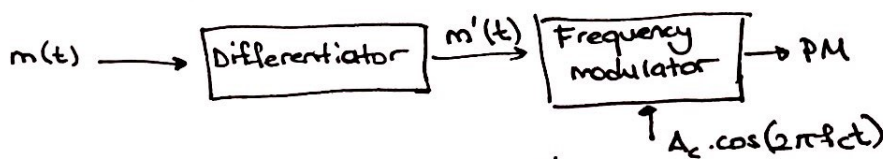
$$s(t) = A_c \cdot \cos(2\pi f_c t + k_p \int_0^t m(\tau) d\tau)$$

- 2. integratör ve faz modulator ile FM işaretini üretirsin

- Generating a PM wave by using a frequency modulator.

Fu meso₂ Isoretin integrolini alin. Frekang modulator.

0 zaman onun girdisine türevini almış gir ki sonunda $m(t)$ yi versin.



$$s(t) = A_c \cdot \cos(2\pi f_c t + 2\pi k_f \int_0^t m'(\tau) d\tau) = A_c \cdot \cos(2\pi f_c t + 2\pi k_f m(t))$$

Summary of Angle Modulation

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Instantaneous
phase $\theta_i(t)$

PM
 $2\pi f_c t + k_p m(t)$

FM
 $2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau$

Instantaneous
freq. $f_i(t)$

PM
 $f_c + \frac{k_p}{2\pi} m'(t)$

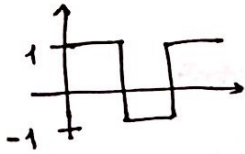
FM
 $f_c + k_f m(t)$

modulated
wave

PM
 $A_c \cos(2\pi f_c t + k_p m(t))$

FM
 $A_c \cos(2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau)$

Example: FM



$k_f = 10^5$
 $f_c = 100 \text{ MHz}$

$$\theta_i(t) = 2\pi \int_0^t f_i(\tau) d\tau = 2\pi \int_0^t f_c + k_f m(\tau) d\tau = 2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau$$

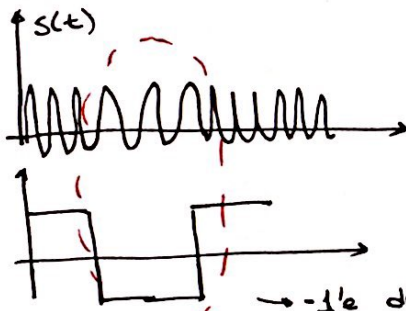
$m(t) = 1$

$m(t) = -1$

$$\theta_i(t) = 2\pi f_c t + 2\pi k_f t = 2\pi(f_c + k_f)t$$

$$\theta_i(t) = 2\pi f_c t - 2\pi k_f t = 2\pi(f_c - k_f)t$$

$$s(t) = \begin{cases} A_c \cos(2\pi(100.1 \times 10^6)t) & m(t) = 1 \\ A_c \cos(2\pi(99.9 \times 10^6)t) & m(t) = -1 \end{cases}$$



frequency shift keying (FSK)

Aynı dıstıle bu sefer PM ile yapalım.

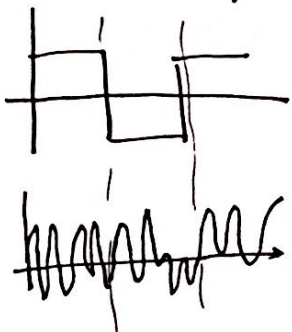
PM $k_p = \frac{\pi}{2}$ $f_c = 100 \text{ MHz}$

$\theta_i(t) = 2\pi f_c t + k_p m(t)$

$m(t) = 1$ $\theta_i(t) = 2\pi f_c t + k_p$

$m(t) = -1$ $\theta_i(t) = 2\pi f_c t - k_p$

$$s(t) = \begin{cases} A_c \cos(2\pi 10^8 t + \frac{\pi}{2}) & m(t) = 1 \\ A_c \cos(2\pi 10^8 t - \frac{\pi}{2}) & m(t) = -1 \end{cases} = \begin{cases} -A_c \cos(2\pi 10^8 t) & m(t) = 1 \\ A_c \cos(2\pi 10^8 t) & m(t) = -1 \end{cases}$$



phase shift keying (PSK)

Frequency modulation

We first consider the simple case of a single tone modulation that produces narrowband FM

We next consider more general case wideband FM

Narrowband FM

$$m(t) = A_m \cos(2\pi f_m t)$$

$$f_i(t) = f_c + k_f A_m \cos(2\pi f_m t)$$

frequency deviator $\Delta f = k_f \cdot \max(|m(t)|) = k_f A_m$
 + tepe degerleinden
 max down al

$$f_i(t) = f_c + \Delta f \cos(2\pi f_m t)$$

$$\theta_i(t) = 2\pi \int_0^t f_i(\tau) d\tau = 2\pi \int_0^t f_c + \Delta f \cos(2\pi f_m \tau) d\tau = 2\pi f_c t + \frac{2\pi \Delta f}{2\pi f_m} \sin(2\pi f_m t)$$

modulation index $\beta = \frac{\Delta f}{f_m}$

$$\theta_i(t) = 2\pi f_c t + \beta \sin(2\pi f_m t)$$

FM wave: $s(t) = A_c \cos(2\pi f_c t + \beta \sin(2\pi f_m t))$

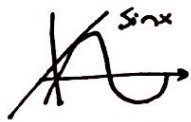
$$\cos(a+b) = \cos(a)\cos(b) - \sin(a)\sin(b)$$

$$s(t) = A_c \cos(2\pi f_c t) \cos(\beta \sin(2\pi f_m t)) - A_c \sin(2\pi f_c t) \sin(\beta \sin(2\pi f_m t))$$

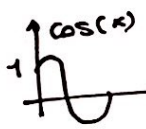
Approximate form of narrowband FM

B'in küçük
değer için

If $\beta \ll 1 \Rightarrow \sin$ da yakın olacak.



$$\sin x \approx x$$



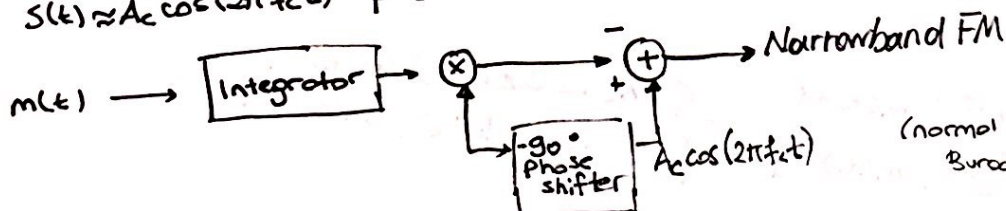
$$\cos x \approx 1$$

} gibi düşünebilirsiniz.

$$\cos(\beta \sin(2\pi f_m t)) \approx 1$$

$$\sin(\beta \sin(2\pi f_m t)) \approx \beta \sin(2\pi f_m t)$$

$$s(t) \approx A_c \cos(2\pi f_c t) - \beta A_c \sin(2\pi f_c t) \sin(2\pi f_m t)$$



(normal FM de genlik sbr = A_c idi)
Burada genlik değırti.

1. The envelope contains a residual amplitude modulation that varies with time.
2. The angle contains harmonic distortion.

$$s(t) = A_c \cos(2\pi f_c t) - \beta A_c \sin(2\pi f_c t) \sin(2\pi f_m t)$$

Polar Baseband Representation of FM

$$s(t) = S_x(t) \cos(2\pi f_c t) - S_y(t) \sin(2\pi f_c t) = a(t) \cos(2\pi f_c t + \phi(t))$$

$$a(t) = \sqrt{S_x^2(t) + S_y^2(t)}$$

envelope

$$\phi(t) = \tan^{-1} \left(\frac{S_y(t)}{S_x(t)} \right)$$

phase

$$\text{Angle: } \theta(t) = 2\pi f_c t + \phi(t)$$

$$\text{Phase: } \phi(t) = \tan^{-1} \beta \sin(2\pi f_m t)$$

For FM signal

$$S_x(t) = A_c, \quad S_y(t) = \beta A_c \sin(2\pi f_m t)$$

$$\text{Envelop: } a(t) = \sqrt{A_c^2 + \beta^2 A_c^2 \sin^2(2\pi f_m t)} = A_c \sqrt{1 + \underbrace{\beta^2 \sin^2(2\pi f_m t)}_{\text{amplitude distortion}}}$$

$$\tan^{-1} x \approx x - \frac{1}{3} x^3$$

$$\phi(t) \approx \beta \sin(2\pi f_m t) - \frac{1}{3} \beta^3 \sin^3(2\pi f_m t)$$

$$\theta(t) = 2\pi f_c t + \beta \sin(2\pi f_m t) - \frac{1}{3} \beta^3 \sin^3(2\pi f_m t)$$

harmonic distortion

Wideband FM

$$\text{FM: } s(t) = A_c \cos(2\pi f_c t + \beta \sin(2\pi f_m t))$$

$s(t)$ is not periodic $s(t) \neq s(t+T)$

Complex Baseband Representation of FM

$$s(t) = \text{Re} \{ A_c \exp \{ j 2\pi f_c t + j \beta \sin(2\pi f_m t) \} \} = \text{Re} \{ A_c \cdot e^{j \beta \sin(2\pi f_m t)} \cdot e^{j 2\pi f_c t} \}$$

$$\tilde{s}(t) = A_c \cdot e^{j \beta \sin(2\pi f_m t)}$$

complex envelope

$$\tilde{s}(t) \text{ is periodic with } T = \frac{1}{f_m}$$

$$\tilde{s}(t+T) \stackrel{?}{=} \tilde{s}(t) = A_c \cdot e^{j \beta \sin(2\pi f_m (t + \frac{1}{f_m}))} = A_c \cdot e^{j \beta \sin(2\pi f_m t + 2\pi)} = A_c \cdot e^{j \beta \sin(2\pi f_m t)}$$

We may therefore expand $\tilde{s}(t)$ in the form of a complex Fourier Series

$$\tilde{s}(t) = \sum_{n=-\infty}^{+\infty} C_n \cdot e^{j 2\pi n f_m t}$$

$$C_n = \frac{1}{T} \int_{-T/2}^{+T/2} \tilde{s}(t) \cdot e^{-j 2\pi n f_m t} dt = \frac{1}{f_m} \int_{-1/2f_m}^{+1/2f_m} A_c \cdot e^{j \beta \sin(2\pi f_m t) - j 2\pi n f_m t} dt$$

$$T = \frac{1}{f_m}$$

$$C_n = \frac{A_c}{2\pi} \int_{-\pi}^{+\pi} e^{j \beta \sin(x) - j n x} dx$$

$$J_n(\beta) = \frac{1}{2\pi} \int_{-\pi}^{+\pi} e^{j \beta \sin(x) - j n x} dx \quad n^{\text{th}} \text{ order Bessel function of the first kind}$$

and argument β .

$$C_n = A_c J_n(\beta)$$

$$\tilde{s}(t) = A_c \cdot \sum_{n=-\infty}^{+\infty} J_n(\beta) e^{j 2\pi n f_m t}$$

FM signal

$$s(t) = \operatorname{Re} \left\{ \hat{s}(t) e^{j2\pi f_c t} \right\} = \operatorname{Re} \left\{ A_c \sum_{n=-\infty}^{+\infty} J_n(\beta) e^{j2\pi(f_c + n f_m)t} \right\} = A_c \sum_{n=-\infty}^{+\infty} J_n(\beta) \cos(2\pi(f_c + n f_m)t)$$

Fourier Spectrum

$$S(f) = \frac{A_c}{2} \sum_{n=-\infty}^{+\infty} J_n(\beta) \left[\delta(f - f_c - n f_m) + \delta(f + f_c + n f_m) \right]$$

Wideband FM

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①

Fourier series expansion of single tone FM signal

$$s(t) = A_c \sum_{n=-\infty}^{\infty} \bar{J}_n(\beta) \cos(2\pi(f_c + n f_m)t)$$

↓
Bessel
fonksiyonu

Fourier spectrum of $s(t)$

$$S(f) = \frac{A_c}{2} \sum_{n=-\infty}^{\infty} \bar{J}_n(\beta) [\delta(f - f_c - n f_m) + \delta(f + f_c + n f_m)]$$

Properties of Bessel function:

1) $\bar{J}_n(\beta) = \bar{J}_{-n}(\beta)$ for n even

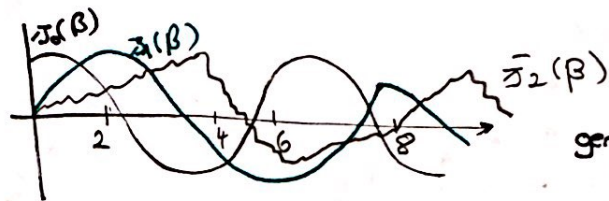
2) $\bar{J}_n(\beta) = -\bar{J}_{-n}(\beta)$ for n odd

3) For small values of β

$$\bar{J}_0(\beta) \approx 1$$

$$\bar{J}_1(\beta) \approx \frac{\beta}{2}$$

$$\bar{J}_n(\beta) \approx 0 \quad n > 1$$

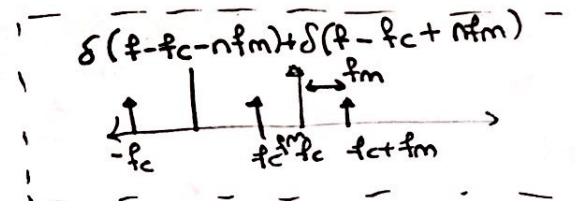


genlikleri
giderek
azalıyor.

3) $\sum_{n=-\infty}^{+\infty} \bar{J}_n^2(\beta) = 1$

Observations

1) The spectrum of FM signal contains a carrier component and an infinite set of side frequencies



2) For small β only Bessel coefficients $\bar{J}_0(\beta)$ and $\bar{J}_1(\beta)$ have significant values (special case - narrow band FM)

FM signal is effectively composed of a carrier a single pair of side freq.

at $f_c \pm f_m$

Average Power of FM signal

$$P = \frac{A_c^2}{2} \sum_{n=-\infty}^{\infty} \bar{J}_n^2(\beta) = \frac{A_c^2}{2}$$

• FM işaretli, işaretin genliğini değiştirmiyor, frekansını değiştiriyor. o yüzden güç de değişmiyor.

FM spectrum for varying amplitude (f_m sabit, A_m değişiyor)

message

$$m(t) = A_m \cos(2\pi f_m t)$$

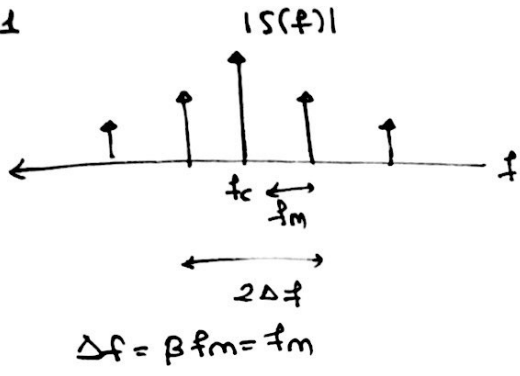
f_m is fixed
 A_m is varied

Frequency deviation
modulation index

$$\Delta f = k_f \cdot A_m$$

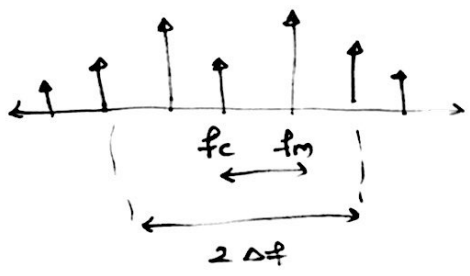
$$\beta = \frac{\Delta f}{f_m} = \frac{k_f A_m}{f_m}$$

$\beta=1$



• f büyüdükçe oklar sıfıra doğru gider.

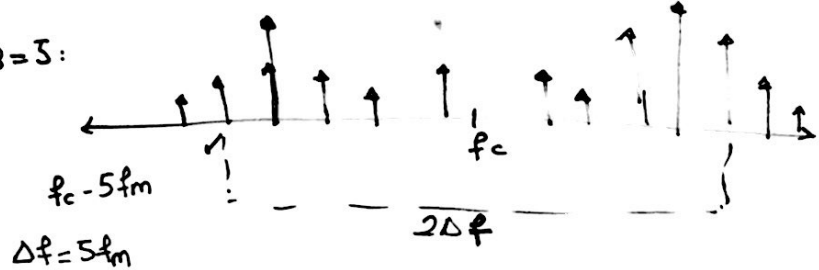
$\beta=2$:



$\Delta f = \beta f_m = 2 f_m$

β arttıkça frekans sapması artıyor.

$\beta=3$:



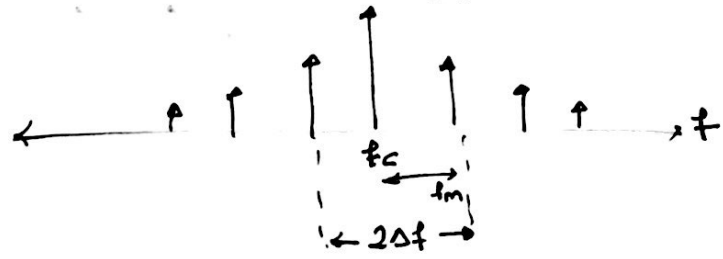
FM Spectrum for varying frequency

$m(t) = A_m \cdot \cos(2\pi f_m t)$

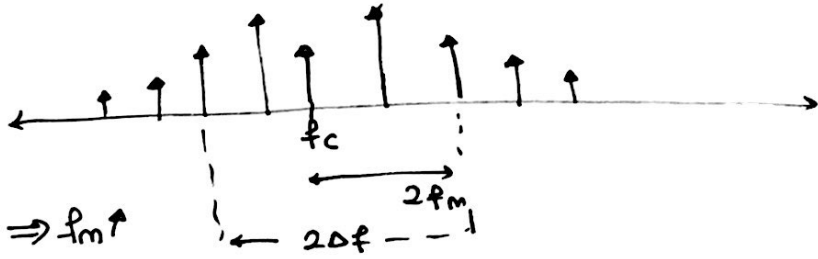
A_m is fixed
 f_m is varied

$\beta = \frac{\Delta f}{f_m} = \frac{k_f \cdot A_m}{f_m}$

$\beta=1$:



$\beta=2$:



$\beta \downarrow \Rightarrow f_m \uparrow$

Bandwidth of $f_m = 2 \Delta f$

Transmission Bandwidth of FM waves

- In theory, an FM wave contains an infinite number of side freq. so that the bandwidth required to transmit such a modulated wave is similarly infinite in extent.
- In practice, however, we find that the FM wave is effectively limited to a finite number of significant side frequencies
- For large values of $\beta \rightarrow \infty$, bandwidth of FM $\rightarrow 2\Delta f$
- For small values of β , spectrum of FM is limited to the carrier freq. and one pair of side frequencies at $f_c \pm f_m$

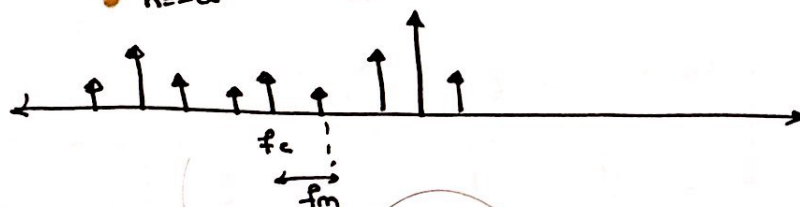
Carson's rule for narrow band FM

An approximate rule for the transmission bandwidth of FM

$$B_T \approx 2\Delta f + 2f_m = 2\Delta f \left(1 + \frac{2f_m}{2\Delta f}\right) = 2\Delta f \left(1 + \frac{1}{\beta}\right)$$

Transmission bandwidth of wideband FM

$$s(f) = \frac{A_c}{2} \sum_{n=-\infty}^{\infty} J_n(\beta) \left[\delta(f - f_c - n f_m) + \delta(f + f_c + n f_m) \right]$$



$$|J_n(\beta)| > 0.01$$

We may define the transmission of an FM wave as the separation between two frequencies beyond which none of the side frequencies are greater than 1 percent of the carrier.

Amplitude obtained when the modulation is removed

Modulation index β	Number of significant side freq. $2n_{max}$
0.1	2
0.5	4
1	6
5	16
10	28

$$B_T = 2n_{max} f_m \quad // \text{single tone wideband}$$

$$\text{where } n_{max} = \max_n |J_n(\beta)|$$

Transmission bandwidth for arbitrary message signal

The highest frequency of $m(t)$ is denoted by ω

$$\text{Deviation ratio: } D = \frac{\Delta f}{\omega}$$

The deviation ratio plays the role for nonsinusoidal modulation that the modulation index β plays for the case of sinusoidal modulation.

Generalized Carson's rule

$$B_T = 2\Delta f + 2W = 2\Delta f \left(1 + \frac{W}{\Delta f}\right) = 2\Delta f \left(1 + \frac{1}{D}\right)$$

example: In North America, the max value of freq. deviation Δf is fixed at 75 kHz for commercial FM broadcasting

If we take $W = 15$ kHz

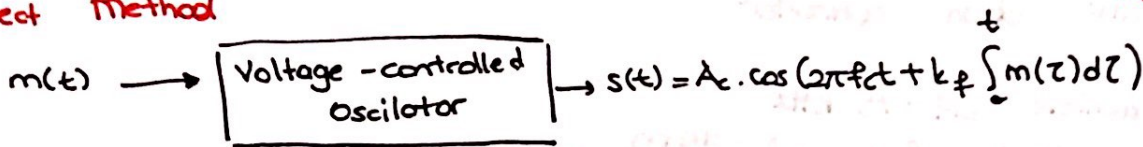
$$\Delta = \frac{\Delta f}{W} = \frac{75 \cdot 10^3}{15 \cdot 10^3} = 5$$

$$B_T = 2(\Delta f + W) = 2(75 \cdot 10^3 + 15 \cdot 10^3) = 180 \text{ kHz}$$

Generation of FM signals

29.11.2016
14:00-16:00

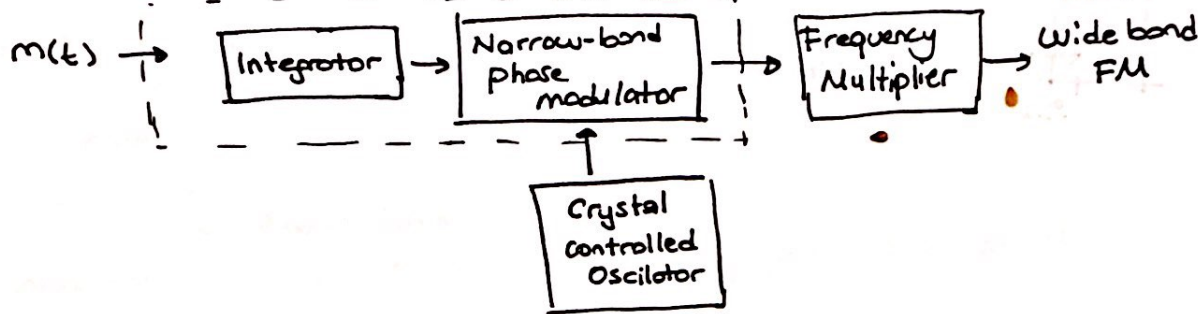
1) Direct Method



Limitations:

- It is capable of providing large frequency deviations
- It has the tendency for the carrier freq. drift.

2) Indirect Method narrowband FM modulator



Frequency Multiplier



$$v(t) = a_1 s(t) + a_2 s^2(t) + \dots + a_n s^n(t)$$

For $n=2$

$$v(t) = a_1 s(t) + a_2 s^2(t)$$

$$s(t) = \cos(2\pi f_c t + 2\pi k_f \int m(\tau) d\tau)$$

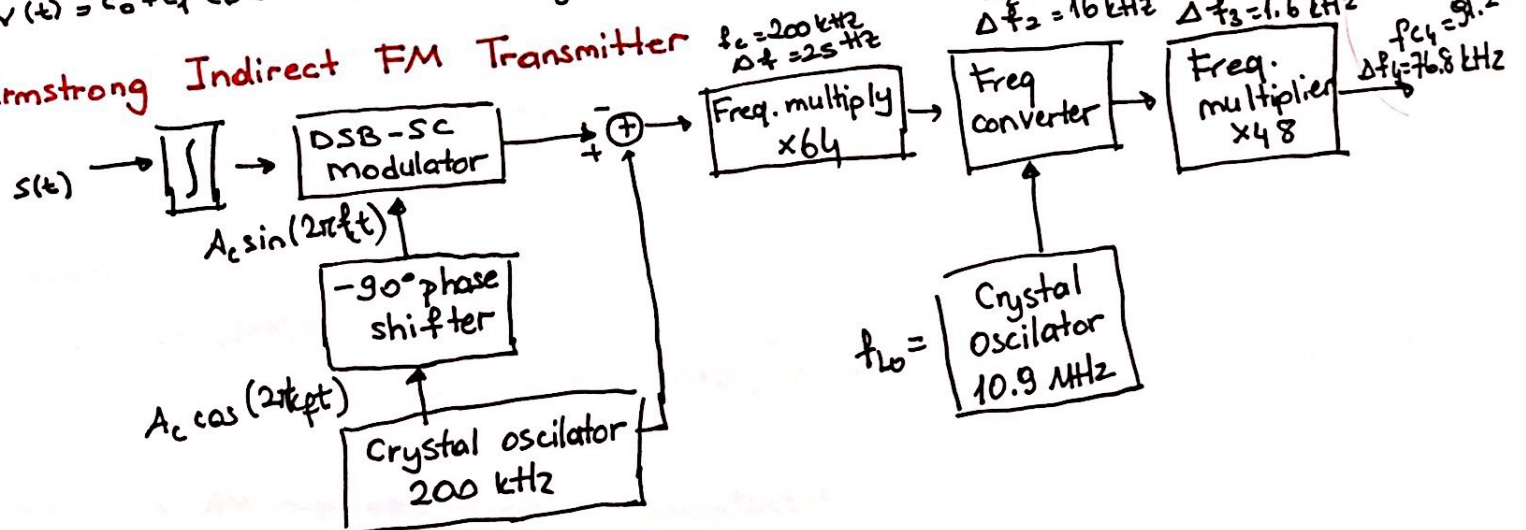
$$v(t) = a_1 \cos(2\pi f_c t + 2\pi k_f \int m(\tau) d\tau) + a_2 \cos^2(2\pi f_c t + 2\pi k_f \int m(\tau) d\tau)$$

$$= \frac{a_2}{2} + a_1 \cos(2\pi f_c t + 2\pi k_f \int m(\tau) d\tau) + \frac{a_2}{2} \cos(4\pi f_c t + 4\pi k_f \int m(\tau) d\tau)$$

General Case

$$v(t) = c_0 + c_1 \cos(2\pi f_c t + 2\pi k_f \int m(\tau) d\tau) + \dots + c_n \cos(n 2\pi f_c t + n 2\pi k_f \int m(\tau) d\tau)$$

Armstrong Indirect FM Transmitter



$f_{c2} + f_{LO} = 23.8 \text{ MHz}$ up converter
 $f_{c2} - f_{LO} = 1.9 \text{ MHz}$ down converter

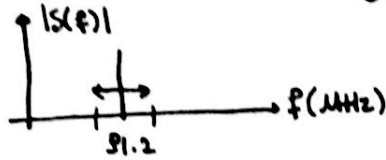
• In order to achieve $\Delta f = 75 \text{ kHz}$

We need a multiplication factor of $\frac{75000}{25} = 3000$

This can be done by using two multipliers, 64 and 48

Total multiplication factor is $64 \times 48 = 3072$ and $\Delta f = 74.8 \text{ kHz}$

Multiplication of $f_c = 200 \text{ kHz}$ by 3072 would yield a final carrier about
600 MHz.



Example: An angle modulated signal $s(t)$ with carrier frequency $f_c = 10^5 \text{ Hz}$ is described by following equation.

$$s(t) = 10 \cdot \cos(2\pi f_c t + 5 \sin 3000t + 10 \sin 2000\pi t)$$

mesaj işareti ($= 2\pi k_f$ mesaj işareti)

- Find the power of modulated signal
- Find the frequency deviation Δf
- Find the deviation ratio D
- Estimate the transmission bandwidth of $s(t)$

a. $P = \frac{A^2}{2} = \frac{10^2}{2} = 50 \text{ watt}$

b. Freq. deviation

frekans sapması

Önce anl. frekansı bulalım

Instantaneous freq. $f_i = \frac{1}{2\pi} \frac{d\phi(t)}{dt} = \frac{1}{2\pi} \frac{d}{dt} (2\pi f_c t + 5 \sin 3000t + 10 \sin 2000\pi t)$

anl. frekans

$$f_i = f_c + \frac{15000}{2\pi} \cos(3000t) + 10000 \cos(2000\pi t)$$

$$\Delta f = \max |f_c - f_i| = \max \left| \frac{15000}{2\pi} \cos(3000t) + 10000 \cos(2000\pi t) \right| = \frac{15000}{2\pi} + 10000 \approx 12,387 \text{ kHz}$$

f_c etrafında bu kadar sapıyor.

c. $D = \frac{\Delta f}{W} \rightarrow$ mesaj işaretinin aldığı max. frekans değeri

mesaj işareti: $5 \sin 3000t + 10 \sin 2000\pi t$
bunu alıyoruz? bunun frekansı daha yüksek

W: Highest freq. component of the message signal

$$W = \frac{2000\pi}{2\pi} = 1000 \text{ Hz}$$

$$D = \frac{12,387 \times 10^3}{10^3} = 12,387$$

d. Single tone değil. Genel durumu alalım.

$$B_T = 2(\Delta f + W) \rightarrow \text{Genel formül}$$

$$= 2(12387 + 1000) = 26774 \text{ Hz}$$

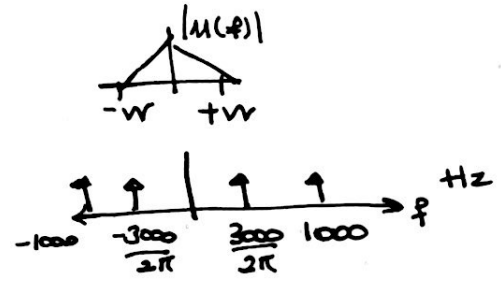
Demodulation of FM signal

1) Frequency Discriminator

$$s(t) = A_c \cdot \cos(2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau)$$

$$\frac{ds(t)}{dt} = A_c (2\pi f_c + 2\pi k_f m(t)) \sin(2\pi f_c t + 2\pi k_f \int_0^t m(\tau) d\tau) = -A_c 2\pi f_c \left(1 + \frac{k_f}{f_c} m(t)\right) \sin(\dots)$$

This is an AM modulated signal, if $\frac{k_f \max |m(t)|}{f_c} < 1$

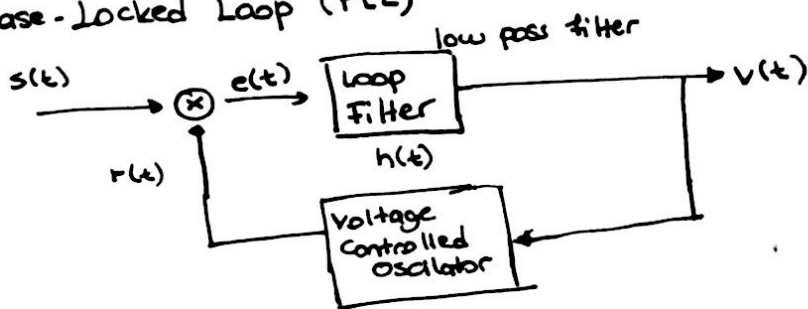


- single tone olsaydı iki tone cos olurdu.
- single tone olsaydı $B_T = 2W$ olacaktı.

We can use envelope detection to extract the message signal.



2) Phase-Locked Loop (PLL)



$$s(t) = A_c \sin(2\pi f_c t + \phi_1(t))$$

$$\phi_1(t) = 2\pi k_f \int_0^t m(\tau) d\tau$$

$$r(t) = A_v \cos(2\pi f_c t + \phi_2(t))$$

$$\phi_2(t) = 2\pi k_v \int_0^t v(\tau) d\tau$$

$$e(t) = s(t)r(t) = A_c A_v \sin(2\pi f_c t + \phi_1(t)) \cos(2\pi f_c t + \phi_2(t))$$

$$v(t) = h(t) * e(t) = \frac{A_c A_v}{2} h(t) * \sin(4\pi f_c t + \phi_1(t) + \phi_2(t))$$

// yüksek frekansı geçirmiyor.

$$= \frac{A_c A_v}{2} h(t) * \sin(\phi_e(t)) = \frac{A_c A_v}{2} h(t) * \sin(\phi_e(t))$$

$$\phi_e(t) = \phi_1(t) - \phi_2(t)$$

$$v(t) = \frac{A_c A_v}{2} \int_{-\infty}^{+\infty} h(t-x) \sin(\phi_e(x)) dx$$

For small $\phi_e(x)$

$\sin(\phi_e(x)) \approx \phi_e(x)$ near-phase-lock

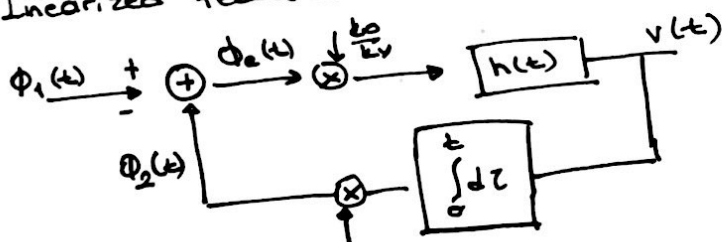
$$v(t) \approx \frac{A_c A_v}{2} \int h(t-x) \phi_e(x) dx$$

$$\approx \frac{k_0}{k_v} \int h(t-x) \phi_e(x) dx$$

$$k_0 = \frac{k_v A_c A_v}{2} \quad \text{loop gain}$$

For $\phi_e(t) = \phi_1(t) - \phi_2(t) = 0$ phase-lock

Linearized feedback model (uygulatılmış geri besleme modeli)



Amaç: faz farkını sıfıra getirmek

$$\phi_2(t) = 2\pi k_v \int_0^t v(\tau) d\tau$$

$$\phi_2'(t) = 2\pi k_v v(t) \rightarrow v(t) = \frac{1}{2\pi k_v} \phi_2'(t)$$

$$\phi_2(t) = \phi_1(t) - \phi_e(t) = 2\pi k_f \int_0^t m(\tau) d\tau - \phi_e(t)$$

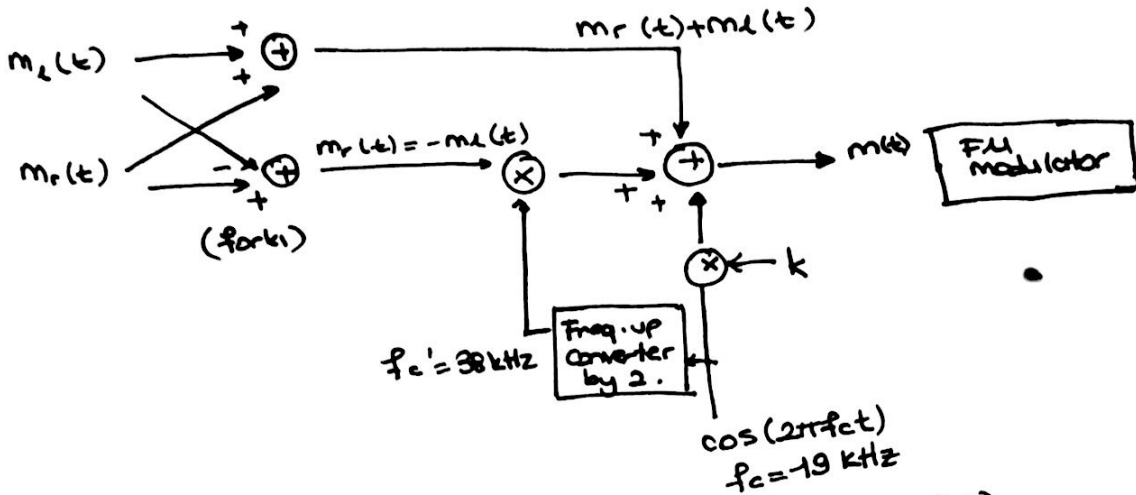
For small: $\phi_e(t) \quad v(t) \approx \frac{k_f}{k_v} m(t)$

Stereo FM

sag ve sol hopörlerden farklı sesler gelebiliyor.

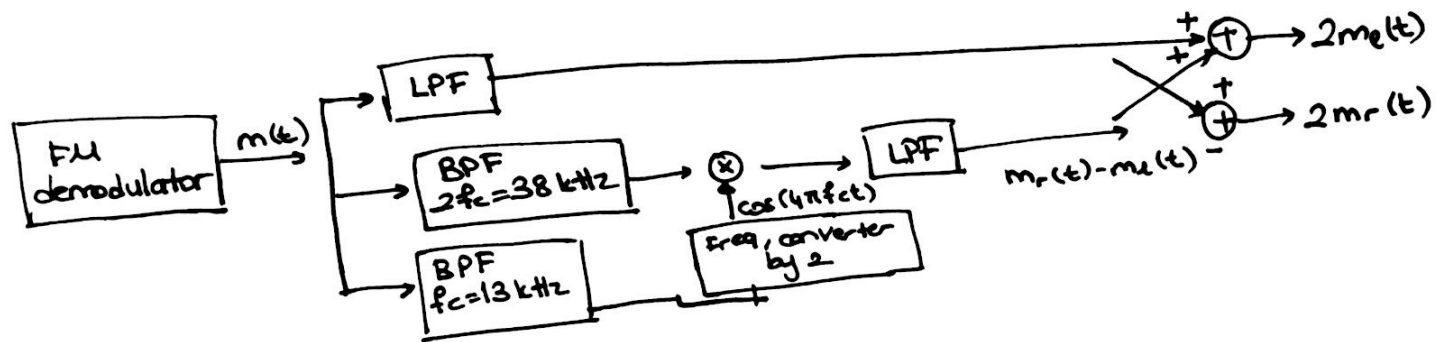
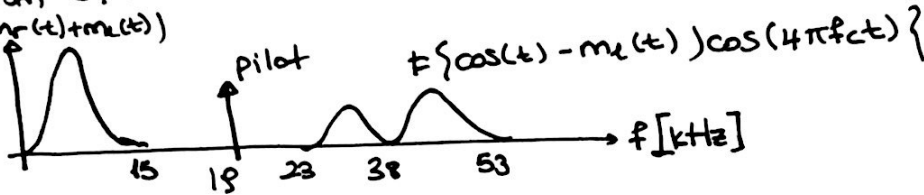
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②

sol mikrofondan kayıt yaptığını: $m_L(t)$
sag mikrofondan " " : $m_R(t)$



$$m(t) = [m_R(t) + m_L(t)] + [m_R(t) - m_L(t)] \cos(4\pi f_c t) + k \cos(2\pi f_c t)$$

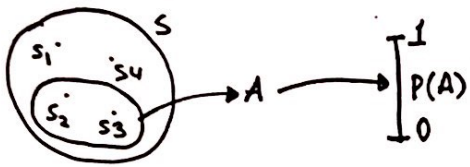
Spectrum of stereo FM



Probability

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Probability triplet $(S, \mathcal{F}, P)$



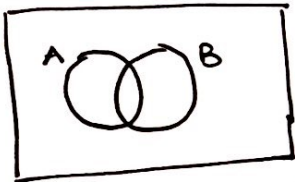
1. Sample space S of elementary outcomes
2. A set $\mathcal{F}$ of events that are subsets of S
3. A probability measure $P(A)$ assigned to each event A in the set $\mathcal{F}$ $A \in \mathcal{F}$

Axioms of Probability

1. $P(A) \geq 0$ for all $A \in \mathcal{F}$
2. $P(S) = 1$
3. If $A_1, A_2, \dots$ are disjoint (or mutually exclusive) events, i.e. $A_i \cap A_j = \emptyset$ the empty set for all $i \neq j$, then $P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$

Conditional probability and Independence

$$P(A/B) = \frac{P(A \cap B)}{P(B)} = \frac{P(A, B)}{P(B)}$$

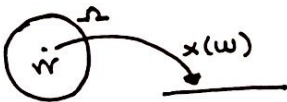


$$P(B \setminus A) = \frac{P(A, B)}{P(A)}$$

Two events are said to be statistically independent iff

$$P(A, B) = P(A) \cdot P(B) \quad // \text{bağımsız (A'nın olması B'yi etkilemiyorsa)}$$

Random Variables



A random variable is a function from sample space Ω to real line

$$x(\omega): \Omega \rightarrow \mathbb{R}$$

- If $x \in \mathbb{R}$, random variable is said to be continuous. It is completely specified by its probability density function (pdf) $f_x(x)$ or its cumulative distribution function (cdf)
- If $x \in \mathbb{Z}$, integer random variable is said to be discrete. It is completely specified by its probability mass function (pmf) $P_x(x)$ or its cdf $F_x(x)$

Cumulative Distribution Function (cdf)

$$F_x(x) = P(X \leq x)$$

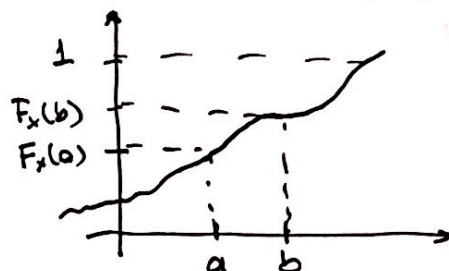
$$F_x(a) = P(X \leq a)$$

Properties

- 1) $F_x(x) \geq 0$ is monotonically nondecreasing.
If $b > a$, then $F_x(b) \geq F_x(a)$

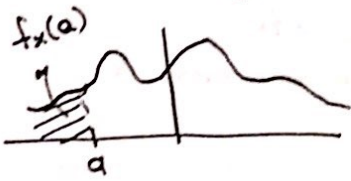
$$P(a < X \leq b) = F_x(b) - F_x(a)$$

$$2) \lim_{x \rightarrow \infty} F_x(x) = 1 \quad \lim_{x \rightarrow -\infty} F_x(x) = 0$$



Probability Density Function (pdf)

$$F_X(x) = \int_{-\infty}^x f_X(t) dt$$



$$f_X(x) = \frac{dF_X(x)}{dx}$$

Properties:

1. $f_X(x) \geq 0$

2. $\int_{-\infty}^{+\infty} f_X(x) dx = 1$

3. $P(x_1 < X \leq x_2) = \int_{x_1}^{x_2} f_X(x) dx$

Expectations:

1. Mean (or first moment)

$$E[X] = \int_{-\infty}^{+\infty} x f_X(x) dx$$

2. Second moment (or quorange power)

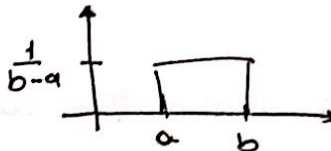
$$E[X^2] = \int_{-\infty}^{+\infty} x^2 f_X(x) dx$$

3. $\text{Var}(X) = E[(X - E[X])^2] = E[X^2] - (E[X])^2$

Uniform random variables

$$X \sim U[a, b] \quad \text{for } b > a$$

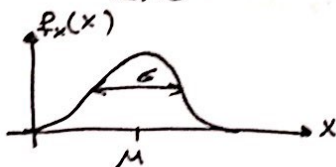
$$f_X(x) = \begin{cases} \frac{1}{b-a} & \text{for } a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$



Gaussian (Normal) random variable

$$X \sim N(\mu, \sigma^2)$$

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$



$$E[X] = \mu \rightarrow \text{beklenenleer}$$

$$\text{Var}(X) = \sigma^2$$

Two random variables

Joint pdf $f_{x,y}(x,y)$

$$P((x,y) \in A) = \iint_{(x,y) \in A} f_{x,y}(x,y) dx dy$$

for a rectangular area

$$P(a < x \leq b, c < y \leq d) = \int_c^d \int_a^b f_{x,y}(x,y) dx dy$$

Properties

- 1) $f_{x,y}(x,y) \geq 0$
- 2) $\int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f_{x,y}(x,y) dx dy = 1$

Marginal pdf

$$f_x(x) = \int_{-\infty}^{+\infty} f_{x,y}(x,y) dy$$

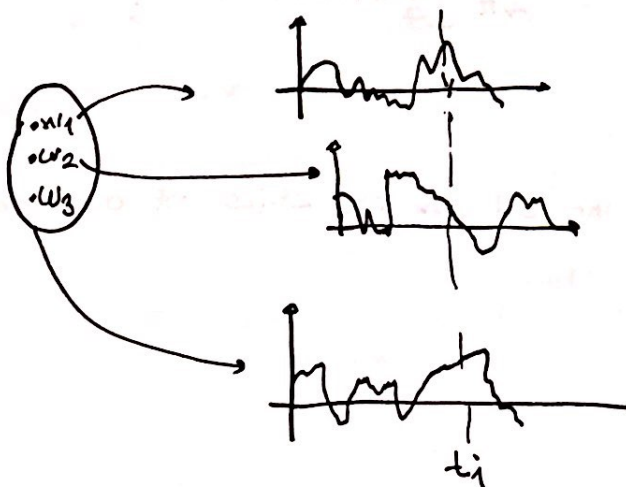
Conditional pdf

$$f_{y|x}(y/x) = \frac{f_{x,y}(x,y)}{f_x(x)} \text{ for } f_x(x) \neq 0$$

Independence: Two continuous random variables are said to be independent if $f_{x,y}(x,y) = f_x(x) \cdot f_y(y)$ for all x,y

Stochastic processes

A stochastic (also called random) process $x(t)$ is an infinite collection of random variables, one for each value of time ($t \in T$)



Zaman sabitleren by rastgele deyişken olmuş olur.

t_1 anında 3 farklı değer alabilir.

Rastgele süreç x Rastgele deyişken açısından farklıdır.

For $t = t_1$ fixed

$x(t_1, \omega)$ is a random variable

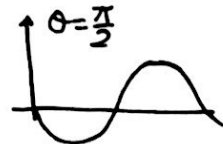
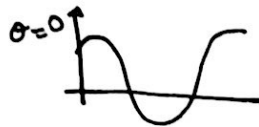
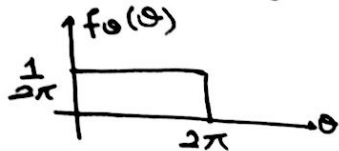
Continuous-time stochastic processes

- A random process is continuous if T is uncountably infinite

Example: Sinusoidal signal with random phase

$$x(t) = \alpha \cos(\omega t + \Theta)$$

$$\Theta \sim U[0, 2\pi]$$



Auto-correlation function of a stochastic process

- For a random process $x(t)$ the first and second order moments are specified by

- mean function $\mu_x(t) = E[x(t)]$

- auto correlation function: $R_x(t_1, t_2) = E[x(t_1)x(t_2)]$

- the auto covariance function

$$C_x(t_1, t_2) = E[(x(t_1) - E[x(t_1)])(x(t_2) - E[x(t_2)])] = R_x(t_1, t_2) - \mu_x(t_1)\mu_x(t_2)$$

Example: Random phase signal

$$x(t) = \alpha \cos(\omega t + \Theta)$$

$$\Theta \sim U[0, 2\pi]$$

$$\begin{aligned} \mu_x(t) &= E[x(t)] = E[\alpha \cos(\omega t + \Theta)] = \int_{-\infty}^{+\infty} \alpha \cos(\omega t + \Theta) f_{\Theta}(\Theta) d\Theta = \int_0^{2\pi} \alpha \cos(\omega t + \Theta) \frac{1}{2\pi} d\Theta \\ &= \frac{\alpha}{2\pi} \sin(\omega t + \Theta) \Big|_0^{2\pi} = 0 \end{aligned}$$

$$\begin{aligned} R_x(t_1, t_2) &= E[x(t_1)x(t_2)] = E[\alpha^2 \cos(\omega t_1 + \Theta) \cos(\omega t_2 + \Theta)] = \int_{-\infty}^{+\infty} \alpha^2 \cos(\omega t_1 + \Theta) \cos(\omega t_2 + \Theta) f_{\Theta}(\Theta) d\Theta \\ &= \frac{\alpha^2}{4\pi} \int_0^{2\pi} \cos(\omega(t_1 + t_2) + 2\Theta) + \cos(\omega(t_1 - t_2)) d\Theta = \frac{\alpha^2}{4\pi} \left[\frac{1}{2} \sin(\omega(t_1 + t_2) + 2\Theta) \Big|_0^{2\pi} + \Theta \cos(\omega(t_1 - t_2)) \Big|_0^{2\pi} \right] \\ &= \frac{\alpha^2}{2} \cos(\omega(t_1 - t_2)) \end{aligned}$$

Stationarity

- Stationarity refers to time invariance of some or all the statistics of a random process.

- we define two types of stationarity (SSS)

strict sense stationary (SSS)

wide " " (WSS)

- A random process $x(t)$ is said to be SSS if all its finite order distributions are time invariant.

Wide sense Stationary (WSS) Random Process

14.12.2016
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(1)

- A random process $X(t)$ is said to be WSS if its mean and autocorrelation functions are time invariant.

$$E[X(t)] = \mu$$

$$R_X(t_1, t_2) = R_X(t_1 - t_2) = R_X(\tau)$$

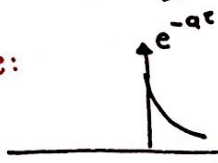
Autocorrelation function of WSS process

1. $R_X(\tau)$ is real and even $R_X(\tau) = R_X(-\tau)$
2. $R_X(\tau) \leq R_X(0) = E[X^2(t)]$ the average power of $X(t)$
3. If $R_X(T) = R_X(0)$ for some T , when $R_X(\tau)$ is periodic with period T and so is $X(t)$

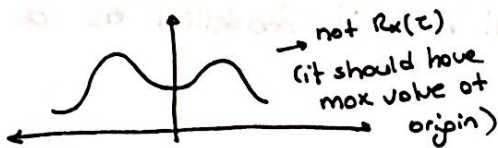
Example: $x(t) = d \cdot \cos(\omega t + \theta)$ random phase

$$R_X(\tau) = \frac{d^2}{2} \cos(\omega \tau)$$

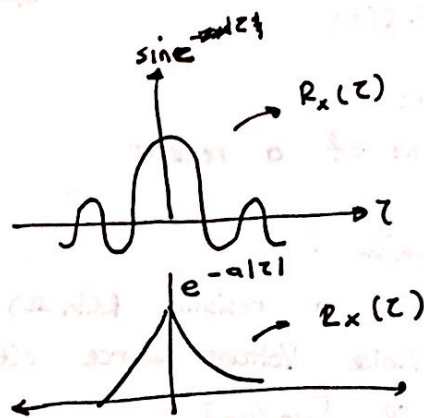
Example:



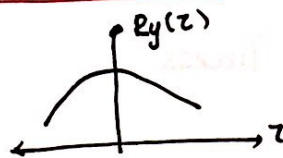
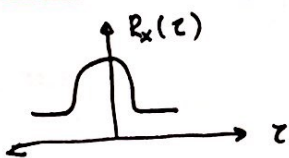
not $R_X(\tau)$
(it is not symmetrical)



not $R_X(\tau)$
(it should have max value at origin)



Interpretation Of Autocorrelation Function



If $R_X(\tau)$ drops quickly with τ , this means that samples become uncorrelated quickly we increase τ .

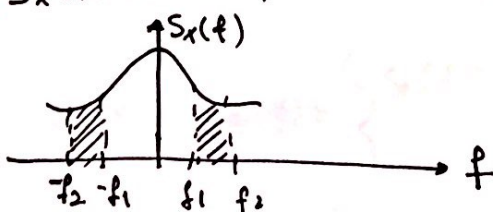
Power Spectral Density (PSD) of a WSS Process

$$S_X(f) = \mathcal{F}\{R_X(\tau)\} = \int_{-\infty}^{+\infty} R_X(\tau) e^{-j2\pi f\tau} d\tau$$

$$R_X(\tau) = \mathcal{F}^{-1}\{S_X(f)\} = \int_{-\infty}^{+\infty} S_X(f) \cdot e^{j2\pi f\tau} df$$

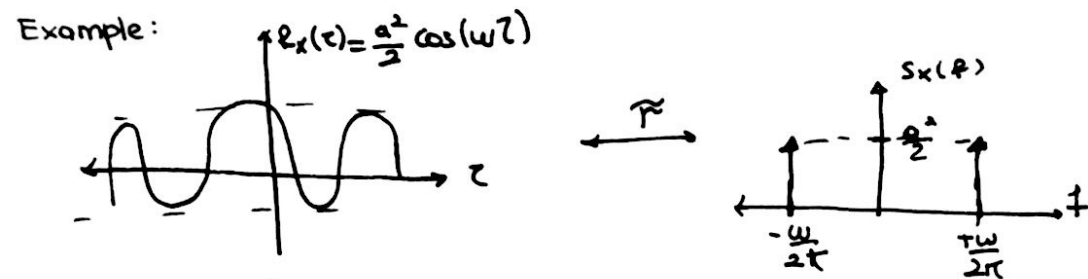
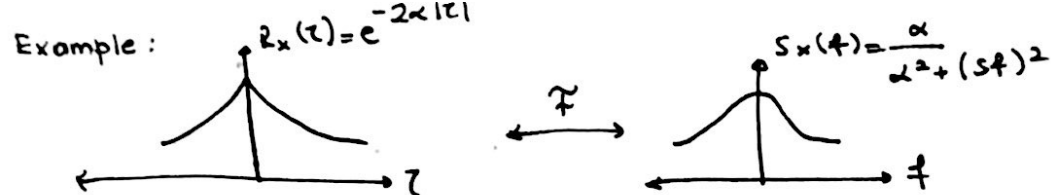
Properties Of PSD

1. $S_X(f)$ is real and even.
2. $S_X(f)$ is the power density. The average power of $x(t)$ in frequency band $[f_1, f_2]$ is

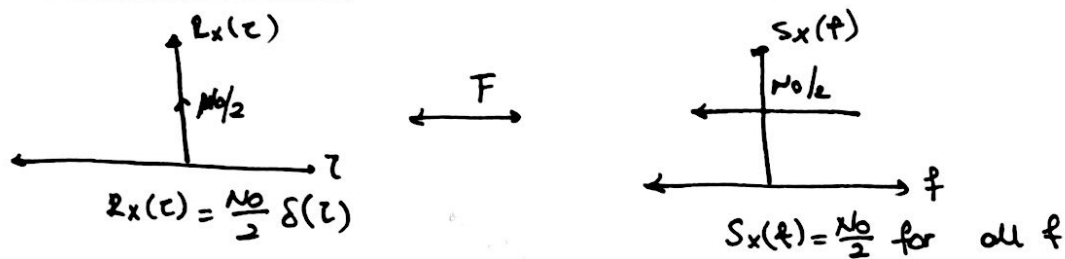


The average power of $x(t)$

$$E[X^2(t)] = \int_{-\infty}^{+\infty} S_X(f) df$$



White Noise Process



Thermal Noise:

Noise equivalent of a resistor



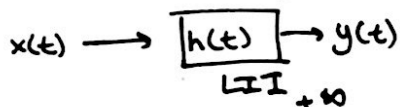
The noise in a resistor R (in Ω) due to thermal noise is modelled as a white Gaussian Noise Voltage source $v(t)$ with psd.

$$S_v(f) = 2kT R \quad [V^2/Hz]$$

k : Boltzman constant

T : Temperature [Kelvin]

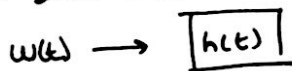
Response of LTI System to DUS Process



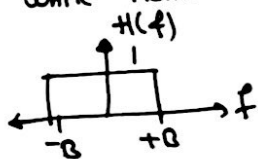
$$y(t) = x(t) * h(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$$

$$S_y(f) = |H(f)|^2 \cdot S_x(f)$$

Ideal Low-Pass Filtered White Noise.



white noise with psd $\frac{N_0}{2}$ for all f



$$a) S_N(f) = |H(f)|^2 S_x(f) = \begin{cases} \frac{N_0}{2}, & -B < f < B \\ 0, & \text{otherwise} \end{cases}$$

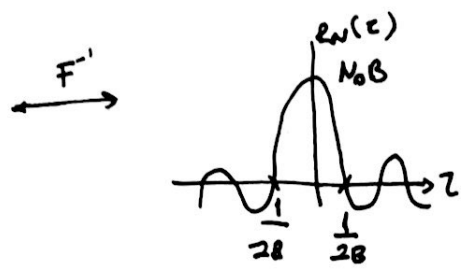
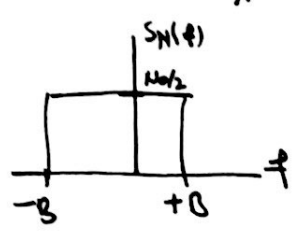
$$S_N(f) = \frac{N_0}{2} \text{rect}\left(\frac{f}{2B}\right)$$

b) Average power of $x(t)$

$$E[N^2(t)] = \int_{-\infty}^{+\infty} S_N(f) df = \int_{-B}^{+B} \frac{N_0}{2} df = N_0 B$$

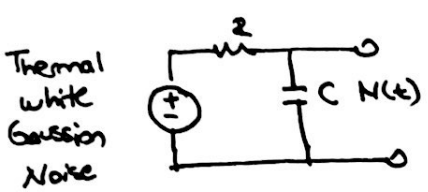
$$c) R_N(\tau) = \int_{-\infty}^{+\infty} S_N(f) e^{j2\pi f\tau} df = \int_{-B}^{+B} \frac{N_0}{2} e^{j2\pi f\tau} df = \frac{N_0}{2} \left[\frac{1}{j2\pi\tau} e^{j2\pi f\tau} \right]_{-B}^{+B}$$

$$= \frac{N_0}{2} \frac{\sin(2\pi B\tau)}{\pi\tau} = N_0 B \text{sinc}(2B\tau)$$



(Average power of $N(t)$)
 $E[N^2(t)] = R_N(0) = N_0 B$

RC Low-Pass Filtered White Noise



$$H(f) = \frac{1}{1+j2\pi fRC}$$

$$|H(f)|^2 = \frac{1}{1+(2\pi fRC)^2}$$

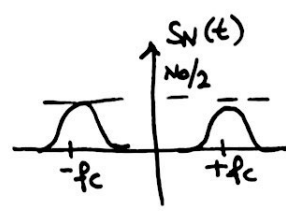
Output PSD $S_N(f) = |H(f)|^2 S_w(f) = \frac{2kTR}{1+(2\pi fRC)^2}$

The average output power

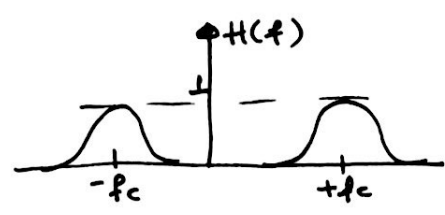
$$E[N^2(t)] = \int_{-\infty}^{+\infty} S_N(f) df = 2kTR \int_{-\infty}^{+\infty} \frac{1}{1+(2\pi fRC)^2} df = \frac{kT}{\pi C} \int_{-\infty}^{+\infty} \frac{1}{1+x^2} dx = \frac{kT}{\pi C} \arctan(x) \Big|_{-\infty}^{+\infty} = \frac{kT}{C}$$

$x = 2\pi fRC$
 $dx = 2\pi RC df$

Narrow Band Noise



white noise process with psd $\frac{N_0}{2}$



$$S_N(f) = |H(f)|^2 S_w(f)$$

$N(t)$ is called narrow-band noise

$$N(t) = N_I(t) \cos(\omega_c t) - N_Q(t) \sin(\omega_c t)$$

$N_I(t)$ = Inphase component of $N(t)$

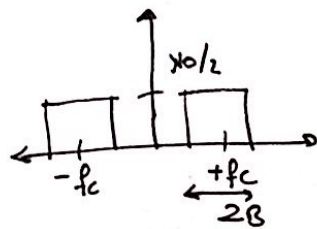
$N_Q(t)$ = quadrature

Properties of $N(t)$

- 1) $N_I(t)$ and $N_Q(t)$ of narrow band noise $N(t)$ have zero mean
- 2) If $N(t)$ is Gaussian, then $N_I(t)$ and $N_Q(t)$ are Gaussian
- 3) If $N(t)$ is stationary, then $N_I(t)$ and $N_Q(t)$ are stationary.
- 4) Both $N_I(t)$ and $N_Q(t)$ have the same psd. This psd is related to the psd of $N(t)$ by

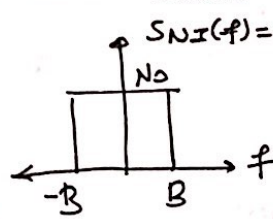
$$S_{N_I}(f) = S_{N_Q}(f) = \begin{cases} S_N(f-f_c) + S_N(f+f_c), & -B \leq f \leq B \\ 0, & \text{otherwise} \end{cases}$$

5. $N_I(t)$ and $N_Q(t)$ have the same variance as $N(t)$



Average power of $N(t)$

Average power of $N_z(t)$

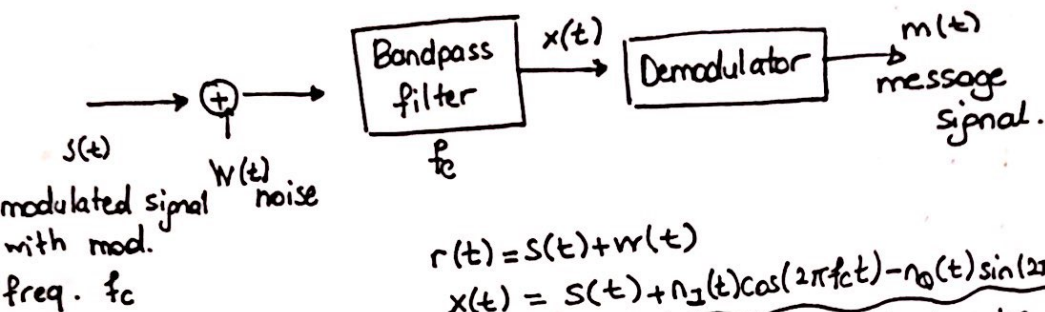


$$E[N^2(t)] = \int_{-\infty}^{+\infty} S_N(f) df = 2 \cdot N_0 \cdot B$$

$$E[N_z^2(t)] = 2N_0 B$$

Noise in Analog Communications

20.12.2016
15:00-16:00
①



$$r(t) = S(t) + w(t)$$

$$x(t) = S(t) + \underbrace{n_1(t)\cos(2\pi f_c t) - n_2(t)\sin(2\pi f_c t)}_{\text{narrow band noise } n(t)}$$

Signal to Noise Ratio (SNR)

$$\text{SNR} = \frac{\text{average power of the signal}}{\text{average power of the noise}} = \frac{E[S^2(t)]}{E[n^2(t)]}$$

Sinusoidal signal in noise:

$$r(t) = A_c \cos(2\pi f_c t) + w(t) \rightarrow w(t) \text{ zero mean with psd } \frac{N_0}{2} \text{ white noise. [W/Hz]}$$

$$x(t) = A_c \cos(2\pi f_c t) + n(t)$$

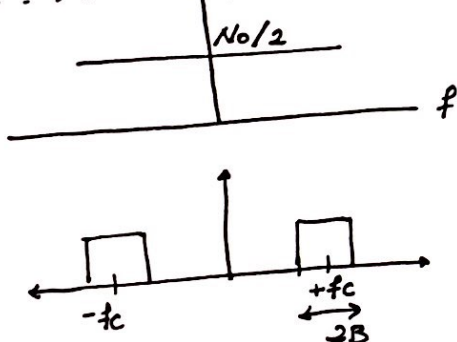
Signal Power:

$$E[S^2(t)] = E[A_c^2 \cos^2(2\pi f_c t)] \text{ by using time average} = \frac{1}{T} \int_0^T A_c^2 \cos^2(2\pi f_c t) dt$$

$$= \frac{A_c^2}{2T} \int_0^T (1 + \cos(4\pi f_c t)) dt = \frac{A_c^2}{2T} \left[t + \frac{\sin(4\pi f_c t)}{4\pi f_c} \right] \Big|_0^T = \frac{A_c^2}{2} W$$

Noise Power:

$$E[n^2(t)] = 2 \cdot \int_{f_c-B}^{f_c+B} \frac{N_0}{2} df$$



$$E[n^2(t)] = \int_{-\infty}^{+\infty} S_n(f) df = 2 \cdot \int_{f_c-B}^{f_c+B} \frac{N_0}{2} df = 2N_0B W$$

$$\text{SNR} = \frac{\frac{A_c^2}{2}}{2N_0B} = \frac{A_c^2}{4N_0B}$$

$$\text{SNR}_{dB} = 10 \log_{10} \text{SNR [dB]}$$

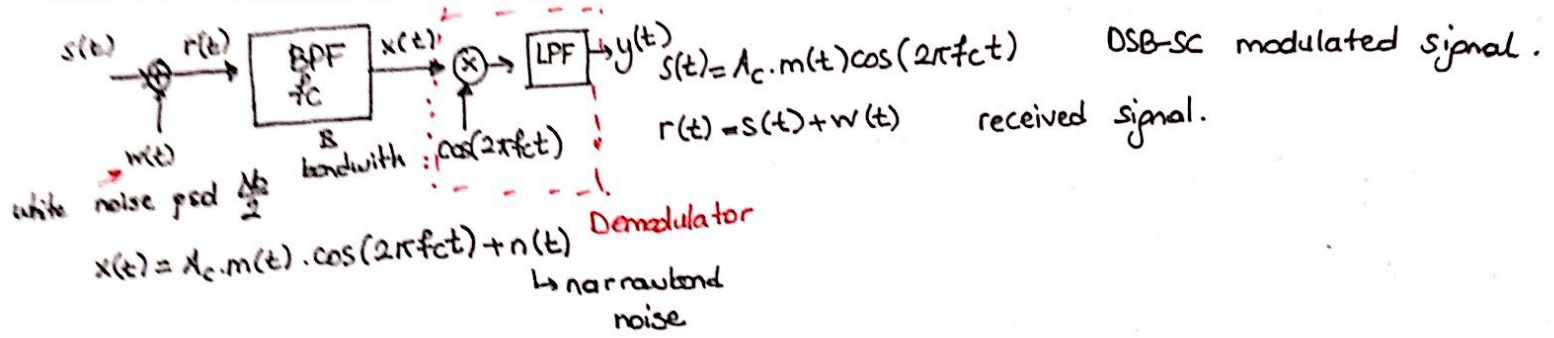
güçleri büyükse SNR negatif çıkar.

Figure of merit



$$\text{Figure of merit} = \frac{\text{SNR}_o}{\text{SNR}_i}$$

DSB-SC modulation in noise



Pre-detection SNE

$$E[s^2(t)] = E[m^2(t) A_c^2 \cos^2(2\pi f_c t)] = E[m^2(t)] \cdot E[A_c^2 \cos^2(2\pi f_c t)]$$

$$= P \frac{A_c^2}{2}$$

$$E[n^2(t)] = 2N_0 B$$

SNRi

$$SNR_i = \frac{E[s^2(t)]}{E[n^2(t)]} = \frac{A_c^2}{4N_0 B}$$

Pre-detection SNE

Output of the mixer

$$v(t) = x(t) \cdot \cos(2\pi f_c t) = \left[A_c \cdot m(t) \cdot \cos(2\pi f_c t) + n_I(t) \cos(2\pi f_c t) - n_Q(t) \sin(2\pi f_c t) \right] \cdot \cos(2\pi f_c t)$$

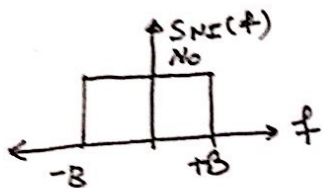
$$= \frac{1}{2} [A_c \cdot m(t) + n_I(t)] + \frac{1}{2} [A_c \cdot m(t) + n_I(t)] \cos(4\pi f_c t) - \frac{1}{2} n_Q(t) \sin(4\pi f_c t)$$

Output of lowpass filter

$$y(t) = \underbrace{\frac{1}{2} A_c m(t)}_{\text{signal}} + \underbrace{\frac{1}{2} n_I(t)}_{\text{noise}}$$

$$E[s_o^2(t)] = E[(A_c \cdot m(t))^2] = A_c^2 \cdot P$$

$$E[n_I^2(t)] = \int_{-\infty}^{+\infty} S_{N_I}(f) df = \int_{-B}^{+B} N_0 \cdot df = 2N_0 B$$



Pre detection SNE : $SNR_o = \frac{\frac{1}{4} \cdot A_c^2 \cdot P}{\frac{1}{4} \cdot 2N_0 B} = \frac{P \cdot A_c^2}{2N_0 B}$

Figure of merit = $\frac{SNR_o}{SNR_i} = 2$

? → yarıncı derstte
kontrol noktası: fıkca
notlarında 1 bulmus.